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## RESEARCH ARTICLE

### DESIGN AND ANALYSIS OF HYDRAULIC POWERPACK AND PUMPS.

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#### Manuscript Info

##### Manuscript History

Received: 10 May 2019  
Final Accepted: 12 June 2019  
Published: July 2019

##### Key words:-

ANSYS, Cycle time, Production efficiency, Productivity, Semi-automatic, VMC.

#### Abstract

This paper is about design and development of hydraulic system for clamping of workpiece on Vertical Machining Center (VMC). Clamping system plays vital role in any manufacturing system it provides good clamping and also increases the production efficiency. So we made a device which overcomes the drawbacks of manual clamping and provides a safe clamping system. This operates on hydraulic principle Pascal's law. Using this we made a hydraulic clamping system which is semi-automatic type clamping system. Which increases productivity and reduces the cycle time of product. We also analyze the component on ANSYS 16 software for various clamping loads on component.

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#### Introduction:-

Our project is to design and analysis of hydraulic power pack and pump for clamping and de-clamping. Basically, it depends upon the hydraulic system. The hydraulic system works on the principle of Pascal's law which says that the pressure in an enclosed fluid is uniform in all the direction. From using the above hydraulic principle, we design the hydraulic power pack for clamping and de-clamping. Hydraulic power packs are stand-alone devices as opposed to a built-in-power for hydraulic machinery. Some power packs are large, stationary units and others are more portable. Since we design the hydraulic power pack which is suitable as well as portable for the above application. Mainly Hydraulic power pack contains some components like motor, pump, control valves, and some auxiliary sections. Most of the industrial hydraulic power pack uses the Vane, Gear and Piston pumps and other pumps are used for Lubricating purpose the standard parts required for hydraulic unit is selected from the standard catalog. After design we implement this system in actual machine finding out various process parameters for the workpiece clamping.

#### Objective

The project objective describes the project's outcomes, intended and direct short- and medium-term effect on the targeted goals.

1. To analyze effect of various force on differential casing using ANSYS 16.0 software.
2. We need to observe the wear rate, heat dissipation, efficient operation about power transmission from motor to pressure creating element i.e. Gear pump. Practical problems like leakage problem, friction between parts.
3. To prepare a device that increases the productivity.

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4. To minimize operations time per product.

### Problem Definition

1. In VMC (vertical machining center) whenever we clamping the job manually there are some drawbacks
2. Less Accuracy (Clamping Force) – Whenever human being applies the force manually on the clamping device it will changes time to time or human to human. Due to these the job/workpiece clamping accuracy is decreases. The human clamping force does not constant.
3. Feedback Loop – When the workpiece clamped on the VMC, the machine and worker both does not get clamping indication i.e. (job is clamped or not).
4. Time Consuming – Whenever the manual clamping is carried out it takes a lot of time for clamping and de-clamping. And also analyzing the clamp is fixed or not.
5. Surface Finish – When the manually clamping is carried out we does not get required surface finish.
6. Others – Whenever the manually clamping is carried out on VMC machine, if workpiece will not be clamped perfectly it will reduce the accuracy of other process that will done on VMC machine.

For manually clamping we always required qualified / skilled labor. From above problems, Maintenance as well as operating cost increases. So, such all problems related to manually clamping, we will be designing an automatic clamping system for that we will moving towards hydraulic system this more accurate also widely used in industry. So, our work is to design hydraulic power pack unit for clamping and de-clamping of workpiece on VMC machine.

### Literature View

**N. P. Maniar et. al.,** [1] reviews locating and clamping considerations, taxonomy of fixture planning & design, also shows an example of fixturing alternatives and characteristics for three types of fixtures i.e. Modular fixturing, General Fixturing, Permanent fixturing. They provide a system view of fixture planning and Design for data & information exchange also gives detailed discussion on CAFD- Computer Aided Fixture Design.

**O.J Bakker et al-** [2]-This paper analysis the latest studies in the field of achieve fixture design and its relationship with flexible clamping and reconfigurable fixture system. In this paper reveals that performance and flexibility are the driver behind the different fixturing contact that have been proposed. Helps to improve accessibility.

**Sunny N Shahane et al-** [3]-This fixture was designed and built to hold support and locate fire tube boiler plate to ensure that it is drilled with accuracy. Which can help in improving productivity and time? This automation reduced the human effort also the design enabled vibration free operation. It increased the productivity and reduced the cycle time of 1 hour to 15 times.

**Sridharkeshava K B et al-** [4]-This paper gives a brief introduction to the general and classic principles of jigs and fixtures Design for Clamping operation. The workpiece location clamping stability under dynamic machining and frictional conditions at the interface between jigs and fixtures elements and workpiece are taken into account-1. Manufacturing considerations 2. Clamping location, pool guiding and workpiece and mounting.

**K.M Viramgama et al-** [5]-This paper will give brief overview if about the 3-2-1 Locating principle to design the fixture for complex parts and other clamping principle. From the study we can conclude that for designing the fixture the geometry method 3-2-1 principle is very useful for the complex component.

**Srinivas R et al -** [6] -A hydraulic system is a group of hydraulic elements arranged in an order and using these hydraulic element powers is transmitted using a confined liquid i.e. Oil. Hydraulic power units are drive system for hydraulic machines.

### Component Details

The component is Bajaj ape differential casing. A differential is device which used for obtaining two different speeds of rear wheels of vehicles while turning. This split type construction having two parts of casing which are attached by means of bolting. The fig no.1 shows the differential casing one part. The component is made up of grey cast iron (ASTM48). This is made by sand casting process. The differential is also known as secondary gearbox of vehicles.

Operations to be performed on differential casing are drilling of four holes and tapping this hole on VMC machine. For that we develop hydraulic clamping system to increase the accuracy of production and for reduction of cycle time.



**Figure no 1:-Bajaj APE differential casing parts.**

### Hydraulic Circuit

A hydraulic circuit is a system which has different interconnection between many hydraulic parts in which the hydraulic liquid is flow and generate power. This power is used to achieve a specific function resulting in work being performed. Before the hydraulic circuit can be designed, the following things must be defined

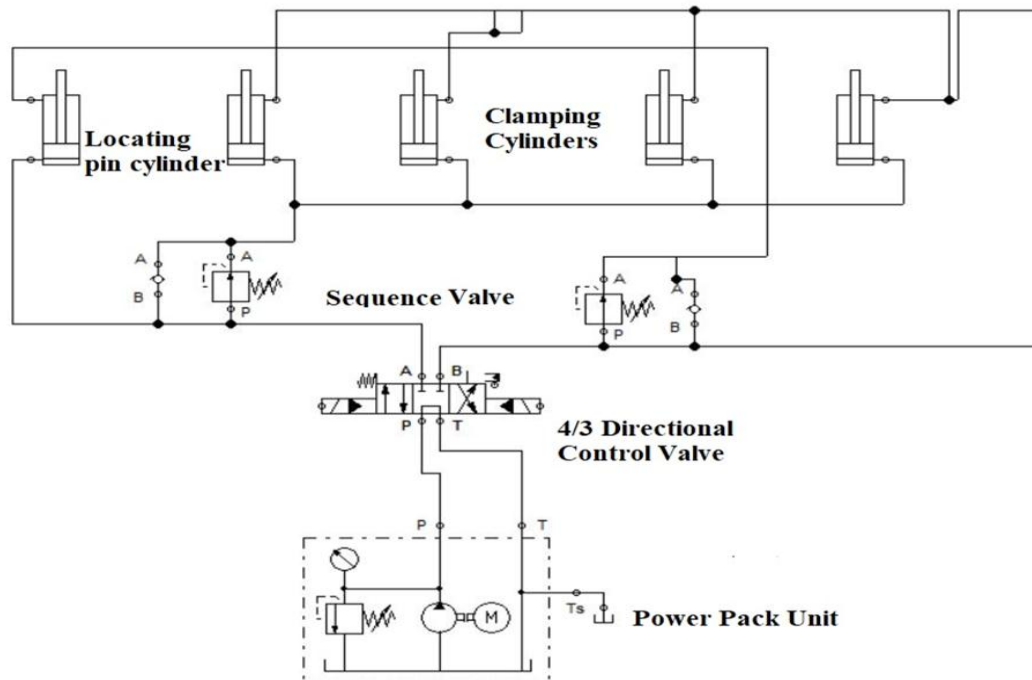
1. The type and number of each type of hydraulic actuator to be used on fixture.
2. The operating pressures required.
3. The sequence of operation.
4. Type of control required.

The circuit comprises the following components:

1. Active components-Hydraulic power pack
2. Transmission lines- Hydraulic pipes
3. Passive components- Hydraulic cylinders

Hydraulic pump is used of output 1.395 LPM. Hydraulic Pump is a device used to impart motion and pressure to the fluid in a hydraulic circuit. Pump is driven by 3 phase, 1hp electric motor to create flow. Pump that creates flow pushes against the piston of a hydraulic cylinder. Directional control valve is one of the most fundamental parts in hydraulic circuit. They allow fluid flow into different paths from one or more sources. Here double solenoid, spring centered and center open type D.C. valve is used. The valve is controlled by an electric current through a solenoid. At center position pressure line is connected to tank line and motor is unloaded. Due to this one can connect or disconnect quick disconnect coupling at center position. Cylinders are linear actuation devices that are typically used to keep a work piece stationary or move work piece into position. They provide axial clamping force proportional to the hydraulic pressure applied. Hydraulic clamp used is of 2.22KN force @ 15Bar, piston diameter is of 45 mm, Stroke is 58. It is important when designing a circuit that all devices including fittings, hoses, valves, tubing have a working pressure compatible with circuit pressure.

Never exceed the maximum operating pressure of any device. If the system flow requirement for clamp time is established with in the restrictions of the largest device, the addition of a flow control will be required to prevent over driving the smaller devices. Hydraulic circuit is shown in fig no.2



**Figure no2:-**hydraulic circuit diagram with different component

### Design

Every mechanical system having some design procedure and we all know which are important things that we want to design for system and this design gives satisfactory work according to calculations. Hydraulic system consists of many parts but from that we want to calculate some important parameter like

1. Hydraulic cylinder
2. Flow rate/ discharge of system
3. Tank capacity

Now for designing of our system we required some basic information, so we have following information.

1. Required Clamping time = 4 sec
2. Required Clamping force = 225 kg
3. Operating pressure = 14 bar Pump and motor

### Design of Hydraulic Cylinder

Force = pressure \* area

Hydraulic cylinder diameter (D) = 45 mm

Clamping force = 2226.60N

Stroke length (l) = 1.3d = 58.5mm

Length of cylinder (L) = 2d = 90mm

### System Flow Rate (Q)

$$\text{Flow rate}(Q) = \frac{\text{volume}}{\text{time}} = 1.395 \text{ LPM}$$

### Tank Capacity

$$\text{Tank capacity} = 4 * \text{flow rate} = 4 * Q$$

$$\text{Tank capacity} = 10 \text{ lit.}$$

### Heating Calculations

$$\begin{aligned} \text{HP} &= \frac{\text{pressure(PSI)} * \text{flow rate(LPHR)}}{1714} \\ &= \frac{203.505 * 0.368}{1714} \end{aligned}$$

$$HP=0.04375 \text{ BTU/ Hrs.}$$

### Finite Element Analysis (Fea) Of Component

Finite element analysis (FEA) is a computerized method for predicting how a product reacts to real word forces, vibrations and other physical effects. Finite element analysis shows whether a product will break, wear out or work the way it was designed. Here we divide the component into small sizes known as element and collective element on the model form mesh. The computer analyses the element and shows collective result. The computer solves by the computational method provided. FEA analysis is done on ANSYS 16.0

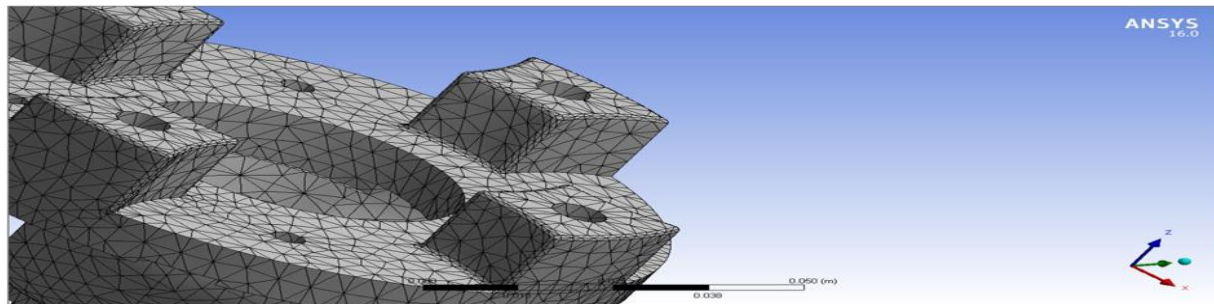
The test results showed that the deflection was within permitted limit or not. For checking whether static and dynamic forces acting over the component are within acquired such that it will provide some of flexibility to it without causing damage to some software are used for it to simulate that designed component are safe or not also whether further improvement is needed. This is done by using ANSYS 16.0 software.

**Table no 1:-Bajaj ape differential casing material**

Sr no	Parameter	value
1	Material	Grey cast iron
2	Nominal composition	C 3.4, si1.8, Mn 0.5
3	Form and condition	cast
4	Yield strength (tensile strength)	330 MPA
5	Elongation	0.5
6	Hardness	260 BHN

### Meshing

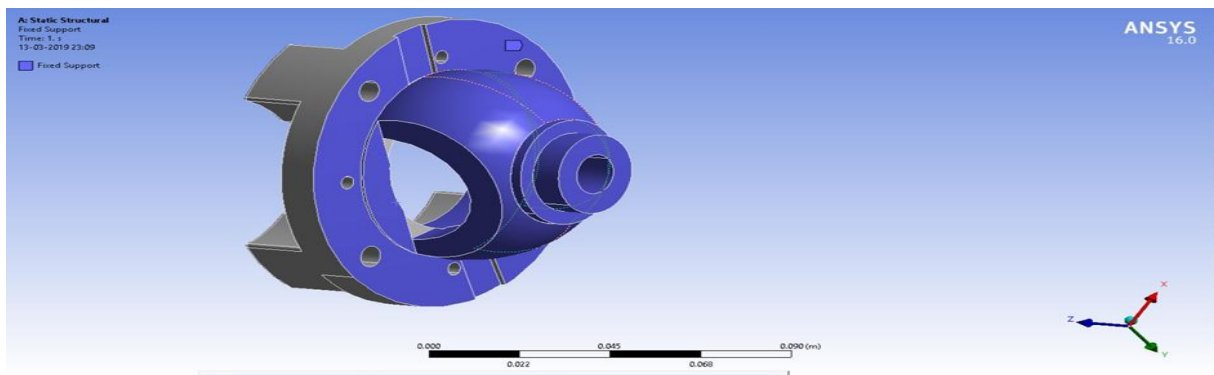
As for analysis whole element is divided into number of parts called as nodes. These nodes are joined to each other to form elements. The process of joining these nodes is called as meshing. We can choose auto mesh mode. This meshing is shown in following figure no 3.



**Fig no 3:-Meshing view of component**

### Fixed Constraint

In this we fix the various parts of the component so that they are fix at time of applications of force following figure shows the fixed part of component which is shown in fig no 4 by blue color



**Figure no 4:-Applying fixed constraint on component**

### Force Constraint

In this we apply force on component also we define the direction of the force. This shown in fig no. 5 by red color. We apply forces on all the four surfaces.

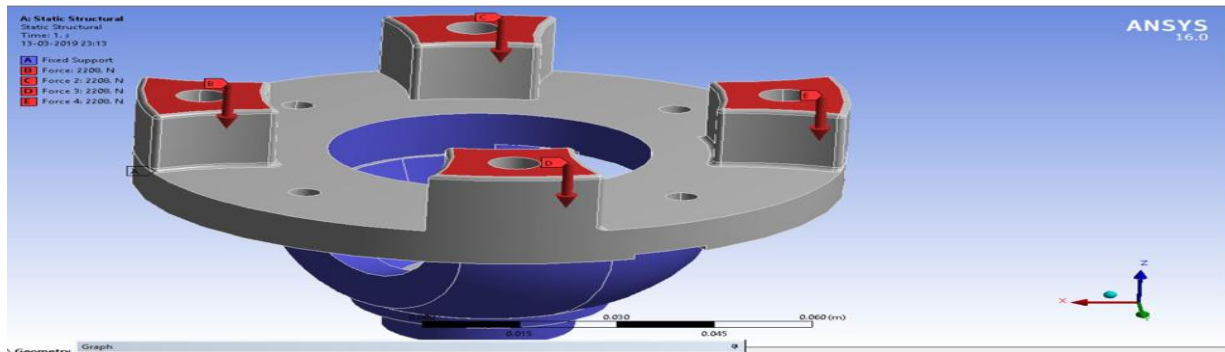


Figure no 5:-Applying force on component

### Stress

After applying force on the component there is tremendous amount of stress is generated which effect on casing which is shown in fig no. 6 and the results obtained from this stress value is shown in table no 2.

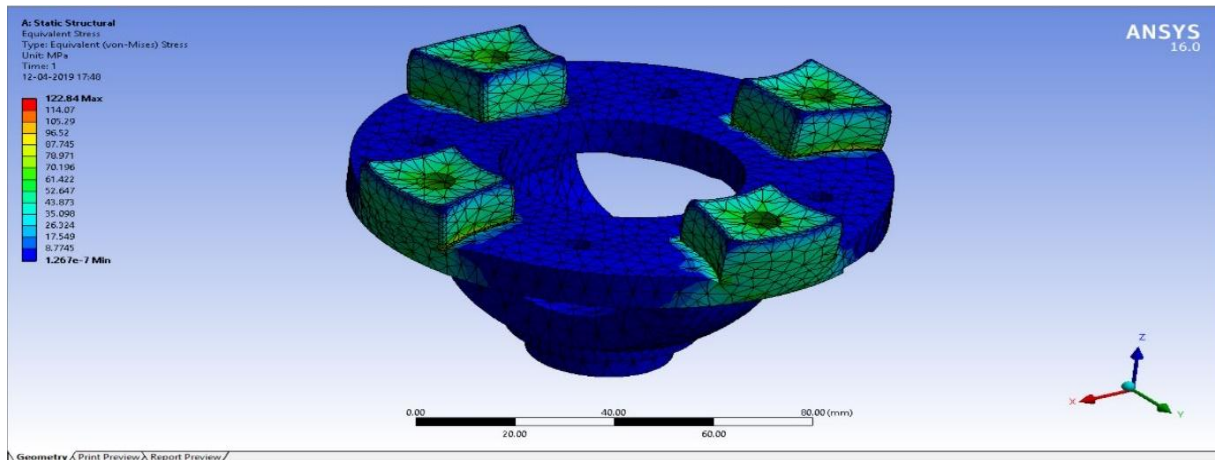


Figure no 6:-Stress generated in the component

Table no 2:-Results from stress value

Max. stress of material	330 MPA
Max. stress developed	122.8 MPA
Factor of safety	2.687

### Strain

Strain is property which shows how much component is elastically strong this result is shown table no. 3 and the generated strain in the component is shown in fig no.7.



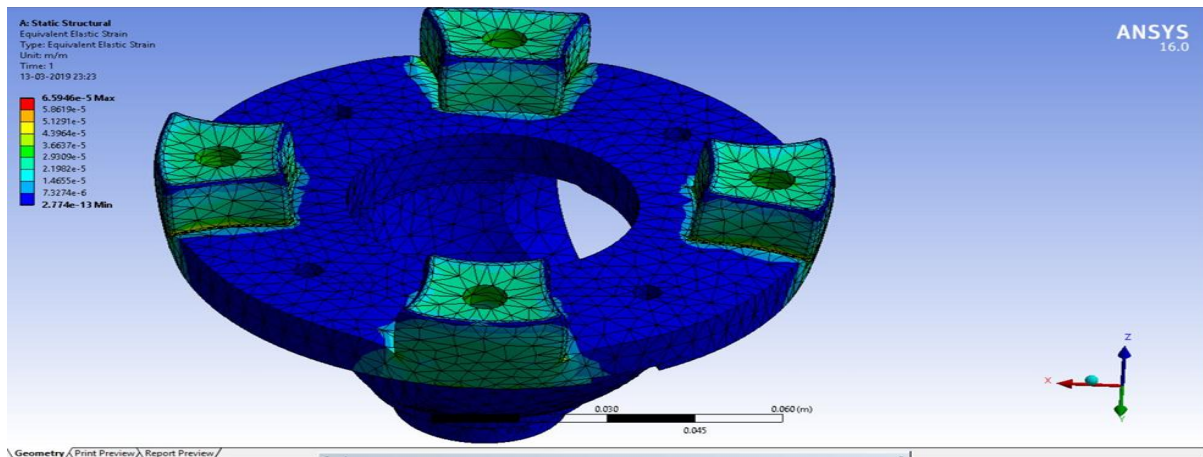


Figure no 7:-Strain generated in component

Table no 3:-Strain value

Parameter	In meter(m/m)	In millimetre (mm/mm)
Strain developed	6.595 e-5	0.06595

### Deformation

Deformation means change in the shape or size of the component due to applied force which show in the following fig no 8 and the value of deformation shown in table no 4.

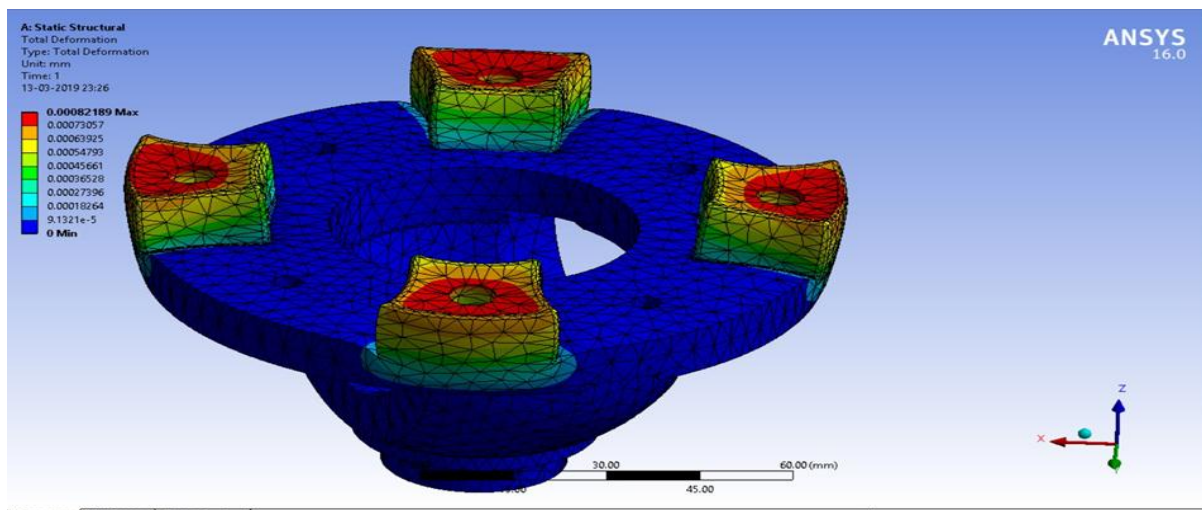


Figure no 8:-Deformation in the component

Table no 4:-Result of deformation

Parameter	In meter (m)	In millimetre(mm)
Total deformation	8.296e-7	0.0008296

In the same we apply different force applied on the casing and we observe the various effect on the differential casing the various value of stress and deformation is give below form that all we can choose 225 kg force because it is recommended by industry but according to our analysis, we also can use force of 250 kg. The value of various deformations and stress are given in table no 5.

**Table no 5:-**Effect of various forces applied on component

Force applied (kg)	Stress developed (MPa)	Total deformation(mm)
225	122.8	0.0008256
250	150.64	0.0009128
500	301.27	0.0018
750	451.91	0.0027
1000	602.25	0.0136

**Result and Discussion:-****Calculations for Manually Fixture****Time required**

Total number of shifts=1

Total working time in shift is 7 hr30 min i.e. 450 min (30 min utilized in lunch break)

Total number of finished products in each shift =45

Processing time= machining time +loading and unloading time+ part travel time (from pallet to fixture or vice versa)  
Now,

1. Machining time (for 4 holes) = 5min
2. Loading time=2 min
3. Unloading time=2min
4. Part travel time=1 min

Therefore, total processing time = 10 min

**Cost of operations**

Cost of finished product= Rs 10/- part

Cost of finished product per shift=  $45 \times 10 = \text{Rs } 450/-$

There are 26 days of working in one month (4 days holiday for breakdown maintenance)

**Therefore**

Annual production cost of finished products=  $450 \times 12 \times 26 = \text{Rs } 1,40,400/-$

**Calculations for Hydraulic Clamping****Time required**

Total processing time includes machining time, clamp actuation and de-actuation time and part travel time. According to standard specification of cylinder, clamping will actuate in 5 sec. Therefore

Processing time= machining time + clamping time and de clamping time + part travel time

Now,

1. Machining time (4 holes) = 5min
2. Loading time =4 sec
3. Unloading time= 4sec
4. Part travel time =1 min

Therefore,

Total processing time =6 min 8 sec

Saving time per part = 3 min 52 sec

Now,

Total number of products produced per shift =65

Increase in number of products=  $65 - 45 = 20$

Increase of production part =20

**Cost of operations**

Cost of finished product= Rs 10/- part



Cost of finished product per shift = Rs 650/-

Annual cost of finished product = Rs 2, 02,800 /-

Annual increase in production cost of finished part = 2, 02,800-1, 40,400

Increase in profit = Rs 62,400 /-

**Table no 6:-**Comparison between existing system and newly employed system

Parameter	Manually system	Hydraulic system
Loading and unloading time	2 min	4 sec
Cycle time	10 min	6 min 8 sec
Finished part/ shift	45	65
Annual cost of finished part	Rs 1,40,400/-	Rs 2,02,800/-
Productivity	Less	Increases

### Conclusions:-

Major benefits of this project to company

1. By using this fixture cycle time reduces by 3 minutes. Cycle time on manual fixture was 10 min and on hydraulic fixture is 6min 8 sec because loading and unloading time is reduced by 50 sec.
2. 45 products are produced per shift on manually operated fixture and 65 products are produced on hydraulic fixture. With the help of this fixture extra 20 parts per shift are produced.
3. By using this system, we save Rs 62400/- per annual.
4. All the values of deformation and von misses stress calculated with ANSYS software is comparatively lower than standard values and hence, we can conclude that design is safe.
5. The proposed clamping system provides the repeatability and high productivity, and also offers a solution which reduces workpiece distortion due to clamping and machining forces.
6. The person from industry will definitely satisfied with the performance of fixture for machining of differential casing because of more benefits compared with conventional process with accuracy and repeatability on VMC

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