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A review and comparative study on task scheduling in group mutual exclusion algorithms to solve critical section problem based on cloud computing

Abstract

6 In large distributed systems which are based on cloud computing, the resources are shared to the 7 clients. There must be some effective task scheduling method which efficiently use the different 8 resources in cloud computing. In most of the algorithms which are based on group mutual 9 exclusion, First come First serve scheduling method is used. But some others scheduling method 10 are also used. These are round robin ,priority scheduling and Johnson sequencing task scheduling 11 and priority based job scheduling. All these are having some advantaged and disadvantages 12 considering the different factors such as SLA. On S and fault talerance

12 considering the different factors such as SLA, QoS and fault tolerance.

In this paper, we present a review and comparative study of different scheduling algorithmswhich best suits for cloud computing.

Keywords: Critical section ,Scheduling methods , Cloud computing, Quality of Service, Groupmutual exclusion.

17 **1.0 Introduction**

Cloud computing model provide on-demand network access to shared resources[1]. The services 18 19 of cloud computing are hosted on a series of virtual machines running over the physical 20 machines. The property of cloud elasticity must be fulfilled. The cloud elasticity is the ability to 21 provide the cloud resources to different processes dynamically. The needs of customers for cloud 22 services are shaped by various aspects, including deadlines, budgetary factors, payment rates, 23 initiation times, duration of execution, and the required quantity of virtual machines. Effective 24 cloud computing involves handling several applications simultaneously and efficiently 25 distributing a range of resources. Resource management systems are essential for distributing 26 resources among different applications, reclaiming resources from finished tasks, and enhancing 27 their deployment to satisfy demand. [2]. Cloud service providers (CSPs) carefully implement 28 resource management techniques, as resources like RAM, memory, processors, I/O devices, 29 extra data centers. As a result, a pay-per-use model is used to provide users with designated 30 amounts of resources, helping to avoid both underutilization and overutilization of resources. To 31 enhance resource utilization and system performance, cloud computing requires the use of 32 effective scheduling strategies. [3]. Cloud service providers aim to ensure effortless access to 33 proficient cooperatives that can support their services and improve the overall cloud 34 infrastructure. Scheduling is aimed to optimize the delivery of cloud services, taking into account 35 the complexities of resource distribution, application deployment, and the fluctuating nature of

36 user requirements. Cloud computing has transformed how customers engage with different cloud 37 tiers, enabling them to implement applications. [4]. A crucial component of this system is the 38 cloud broker, which serves as a platform to gather user data, analyze it, and communicate with 39 Cloud Service Providers (CSPs) on behalf of clients while also providing billing solutions. The 40 cloud broker's ability to integrate information can be effortlessly incorporated into any cloud 41 networking, allowing users to oversee the execution times of their requests, monitor resource 42 usage, and evaluate waiting times. Distributed computing has developed into a virtualized model 43 where applications run transparently, despite the complexities of the cloud infrastructure. [5]. It 44 provides flexible resource allocation and a strong platform to tackle multiple issues, such as 45 effective request handling within a pay-as-you-go framework. [6]. Its dependability, ability to scale, and affordability, cloud computing has become extremely popular in addressing a variety 46 47 of computational issues. [7]. In cloud computing, services are delivered to clients based on a 48 shared understanding between the client and the Cloud Service Provider (CSP). These services 49 are carried out through a series of tasks, leading to the idea of re-serving, where tasks may be 50 redistributed for maximum efficiency. By tackling challenges such as delays in processing 51 clinical requests and optimizing processor and resource use, the scheduling aims to provide 52 valuable insights for advancing cloud computing practices, resulting in better service quality and 53 increased customer satisfaction. Task scheduling in cloud computing is a complex computational 54 challenge known as NP-Complete [8]. The goal of task scheduling is to optimize certain 55 parameters like resource utilization, and power consumption by establishing the sequence in 56 which tasks are performed on virtual machines. Companies that specialize in cloud services 57 utilize various types of machines in their data centers to deliver timely services.

58 **Objective of the study:**

In this paper, we have presented a comparative study of various task scheduling algorithms in
the context of cloud computing. The different algorithms used for task scheduling are FirstCome-First-Serve (FCFS), Round Robin, and Priority Scheduling .

62 2.0 Related Work:

63 The problem of GME was firstly given by Yuh-Jeer Joung[9]. Joung proposed two different 64 algorithm for GME. These are Joung's broadcast based algorithm[10] and Joung's quorum based algorithm[11]. Joung's broadcast based algorithm was an extension of Ricart and Agarwala 65 66 distributed mutual exclusion algorithm^[12]. Joung proposed two algorithms RA1 and RA2. In RA1, the process which wants to enter the critical section, sends a request message to all the 67 68 processes and upon receiving reply message from all the processes, it enters the critical section. There are some concurrency related issues in RA1, which was later solved by using RA2. In 69 70 Joung's quorum based algorithm, the concept of quorum is used. A process has to obtain 71 permission from all the processes in the quorum to enter critical section. For concurrency, Joung 72 proposed two algorithms, the first one is Maekawa M, which sends message in parallel and

- second one is serial version called Maekawa_S, which obtains sequential permission from each
 process in quorum. These two algorithms avoids deadlock .
- In comparison to classical distributed systems, the working in cloud computing is different because it deals with different characteristics. The different characteristics in cloud computing includes fault-tolerance, QoS, scalability and priority. There are different priority based algorithms which are used for real time systems. These can be categorized as :
- 79 (i)Static priority algorithms (ii) Dynamic priority algorithms.
- The priority in static priority algorithms remains the same. There is no priority inversions but it can lead to starvation as low priority processes cannot be able to enter the critical section. Housni and trehel[13] proposed an algorithm where sites with same priority forms the group. It uses router for external communication and the processes within the group communicate with each other by passing messages. When any process wants to enter the critical section, it sends the request and that request is forwarded to the root. The root sends the token request to the routers.
- 86 In each group, the Raymond algorithm[14] is used.
- In dynamic priority algorithms, the priority of algorithm is increased with the passage of time. 87 88 For increasing the priorities, different factors such as request time, level and distance are used in 89 different algorithms. In Kanrar-Chaki [15] token based algorithm, which is based on Raymond 90 algorithm[14], the low priorities of pending requests are increased dynamically. In avoids 91 starvation but increases priority inversions. Jonathan Lejeunl et al[16] proposed a token based 92 algorithm where new concepts have been added in Kanrar-Chaki[15] token based algorithm. 93 These are level heuristics and level distance heuristics. Level heuristics postpones the priority 94 increment of pending requests. In level distance heuristics, the processes are incremented 95 according to the level of the tree. These two heuristics removes the drawbacks of the Kanrar-96 Chaki[15] token based algorithm where the low priority processes frequently access the critical 97 section which is priority inversion. In priority inversions, a low priority process has been granted 98 the access to critical section before the high priority process which is violation of Service Level 99 Agreement. Jonathan Lejeunl et al[16] proposed a new algorithm where the attempt is balance 100 the priority inversions and response time of low priority processes. It uses the awareness concept 101 which aims at reducing maximum response time whereas the number of priority inversions 102 remains low. For this global view of pending requests is necessary.
- Task scheduling plays a vital role in distributed computing settings, especially within cloud computing. Efficient scheduling techniques strive to reduce task waiting periods and improve overall cloud performance to maximize advantages. The goal of utilizing different scheduling algorithms is to determine a suitable task sequence that shortens the total execution time. Considering the distributed and diverse characteristics of cloud environments, conventional scheduling algorithms may not be suitable for direct application. Therefore, it is important to create scheduling algorithms designed specifically for cloud systems. [17]. By tackling the

110 specific challenges presented by cloud environments, these tailored scheduling algorithms can 111 improve resource management, decrease latencies, and enhance overall system performance. 112 ultimately resulting in greater advantages for both cloud service providers and users. Effective 113 task scheduling is vital for unlocking the complete potential of cloud computing and fulfilling the 114 increasing demands of various applications and services in the digital age. As researchers, it is 115 essential to investigate new and efficient scheduling algorithms designed for cloud environments 116 to continually improve cloud services and promote progress in the field of distributed computing. 117 In the field of virtual machine (VM) selection for application scheduling, Naik et al. [18] 118 introduced a novel hybrid multiobjective heuristic method that combines the Non-dominated 119 Sorting Genetic Algorithm-2 (NSGA-II) with the Gravitational Search Algorithm (GSA). This 120 hybrid strategy aims to improve both the efficiency and efficacy of the scheduling process by 121 leveraging the advantages of NSGA-II and GSA. While GSA focuses on utilizing effective 122 solutions to search for optimal results and avoid becoming stagnant, NSGA-II expands the 123 exploration range through a thorough investigation. The main goal of this hybrid approach is to 124 achieve better job scheduling performance, concentrating on three essential factors: maximizing 125 the total number of scheduled jobs, reducing overall energy consumption, and achieving the 126 shortest response time alongside the lowest cost. It is crucial to recognize that current scheduling 127 algorithms in VMs do not cater to the specific needs and goals that this hybrid approach 128 considers. Consequently, the suggested integration of NSGA-II and GSA presents an innovative 129 and promising method for tackling the challenges associated with VM selection and application 130 scheduling, which may enhance cloud computing performance and resource efficiency. In the 131 field of public cloud computing, a variety of heuristic algorithms have been created and utilized 132 to efficiently schedule a range of jobs. Among the most significant developments in heuristic 133 methods are the First Come, First Serve (FCFS) algorithm, the Min-Max algorithm, the MinMin 134 algorithm, and the Suffrage computation. Furthermore, other notable innovations in this area include Greedy Scheduling, Shortest Task First (STF), Sequence Scheduling, Balance 135 136 Scheduling (BS), Opportunistic Load Balancing, and Min-Min Opportunistic Load Balancing 137 [19], [20], [21]. These heuristic algorithms are vital for task scheduling within the public cloud, focusing on optimizing various performance metrics such as job completion times, resource 138 139 utilization, and system effectiveness. Each algorithm tackles the scheduling challenge from a 140 unique angle, applying specific rules and strategies to meet the intended goals.

141 **3.0 Analysis of different Scheduling algorithms:**

142 **First Come First Serve algorithm:**

The First-Come-First-Served (FCFS) scheduling algorithm functions by executing tasks in the sequence they are received, employing a non-preemptive strategy. The average waiting time and overall turnaround time for tasks are affected by their size and the timing of their arrival. In a cloud computing setting, several clients seek resources from the data center controller, and these requests are sent to the FCFS virtual machine load balancer. The FCFS virtual machine load balancer processes tasks according to the order in which client requests arrive, [22], [23], [24].

149 The FCFS approach has been extensively researched and utilized in cloud computing because of

150 its simplicity and equitable resource distribution based on arrival times. Nonetheless, it may

151 result in suboptimal resource usage and increased wait times for tasks of different sizes and

152 priorities. To mitigate these drawbacks, scholars have investigated alternative task scheduling

153 methods, such as Round Robin, Priority Scheduling, and Johnson Sequencing, each presenting

154 unique benefits and specific strategies to enhance cloud resource management and performance.

155 Priority Scheduling algorithm:

156 The Priority Scheduling algorithm functions by executing tasks according to their designated 157 priorities, with tasks of higher priority being processed before those of lower priority. This 158 scheduling method is often utilized in operating systems that manage numerous tasks, where the 159 order of execution is influenced by their priority levels. Priority Scheduling can also be applied 160 as a preemptive strategy, enabling a higher priority task to interrupt and take over the execution 161 of tasks with lower priority, [25], [26], [27], [28]. The priority-driven method of task scheduling 162 is beneficial for real-time systems and applications that require certain tasks to be prioritized 163 based on their importance or urgency. However, implementing priority scheduling may result in 164 challenges such as starvation, where lower priority tasks experience significant delays in being 165 executed. It is crucial to strike a balance in priority levels and take task attributes into account to 166 ensure equitable resource distribution and avoid scenarios where low-priority tasks are 167 indefinitely postponed. As the study of task scheduling in cloud computing progresses, it is 168 important to investigate the performance of different scheduling algorithms, including Priority 169 Scheduling, across various circumstances, workload distributions, and system setups.

170 Priority Scheduling Algorithm, follows these steps:

Initialization: The process starts by setting up the list of tasks along with their respective
 priorities. Each task is depicted as a job or process, with its priority determined by established
 criteria, including the significance of the task, deadline requirements, or preferences set by the
 user.

Sort Tasks: The subsequent step involves arranging the list of tasks according to their
 priorities, with higher priorities listed first. This arrangement guarantees that tasks with greater
 importance are positioned at the beginning of the list, while those of lesser importance are
 located towards the end.

• Execution: The algorithm executes tasks based on their priority levels. The task that has the highest priority is chosen first for execution. The manner of execution can differ based on whether the algorithm operates in a preemptive or non-preemptive manner. In a preemptive algorithm, a currently executing task can be interrupted if a task with a higher priority arrives. The system continuously monitors for any higher priority tasks that may arise during the execution of a task. If a higher priority task is detected, the current task is interrupted, and the higher priority task is scheduled to run. In non-preemptive mode, the current task is permitted to

- 186 finish executing before selecting and scheduling the next task with the highest priority.
- Task Completion: After a task is finished, the algorithm moves on to the subsequent task
 following the established priority sequence. This cycle continues until all tasks have been carried
 out.
- Task Arrival: When carrying out tasks, it is possible for new tasks to enter the system. In the case of a preemptive algorithm, the priority of the new task is assessed against the priority of the task currently in progress. If the new task's priority is greater, it interrupts the ongoing task, and
- 193 the new task is then scheduled for execution.
- Task Termination: When tasks finish executing, they are taken off the list, and the algorithm
 proceeds to choose the next task with the highest priority for execution.
- Completion Check: The algorithm carries on performing tasks until every task in the list has
 been finished. After all tasks have been executed, the scheduling procedure comes to an end.
- 198 Round Robin Scheduling algorithm:

The Round-Robin (RR) scheduling algorithm is a basic preemptive scheduling method used in 199 200 different computing environments. In RR, each process is assigned a specific time quantum or 201 time slice by the CPU. The processes are managed in a First-Come-First-Serve (FCFS) order, 202 allowing them to run for the length of the time quantum. After the time quantum expires, the 203 current process is interrupted, and the CPU shifts to the next process in line. This preemption and 204 switching between tasks persist until all processes in the system have finished their execution. 205 The RR scheduling algorithm is commonly utilized in operating systems and distributed 206 computing settings due to its straightforwardness and equitable resource distribution. It 207 guarantees that every task receives an equitable portion of the CPU's time, thereby preventing 208 any single task from dominating the CPU for too long. By implementing a fixed time quantum, 209 RR achieves a balance between responsiveness and efficiency in executing tasks. The main 210 characteristics of the Round-Robin scheduling algorithm include the following:

- Preemptive Scheduling: RR functions as a preemptive scheduling algorithm, enabling tasks to be interrupted and rescheduled even if they haven't completely used their time quantum. This capability facilitates a flexible and responsive distribution of resources.
- Time Quantum: The time quantum is an essential factor in the RR algorithm. It defines the duration for which each task can execute before being interrupted. Selecting the right time quantum affects the trade-off between system responsiveness and the overhead caused by context switching.

- FCFS Order: Tasks are organized in a queue according to their arrival time, and the RR algorithm executes them following the FCFS sequence. This guarantees that tasks are processed in the order of their arrival, promoting fairness in the distribution of resources.
- Preemption Handling: When a task's time slice runs out, the processor records its current state and transitions to the following task in the queue. The interrupted task is then placed at the end of the line to wait for its next opportunity.
- The Round-Robin scheduling algorithm offers a viable method for organizing tasks across different computing settings. Nevertheless, its efficiency can be affected by factors such as the selected time quantum, the characteristics of the tasks being processed, and the total system load. Ongoing research is dedicated to investigating modifications and improvements to RR to boost its performance and flexibility in various situations [29], [30], [31].
- 229 DYNAMIC HEURISTIC JOHNSON SEQUENCING ALGORITHM :
- The Dynamic Heuristic Johnson Sequencing (DHJS) algorithm presents an innovative method that integrates the calculation of dynamic burst time and the Johnson sequencing technique to enhance task scheduling in a multi-server setting. Initially, the DHJS algorithm computes the dynamic time quantum for the tasks using the median burst time and the maximum burst time of the tasks. This time quantum is then implemented in a Round Robin scheduling method. Following this, the Johnson sequencing algorithm is utilized to establish the optimal order for executing the tasks.
- The DHJS algorithm offers a flexible and heuristic method to tackle intricate task scheduling problems in multi-server settings. By integrating burst time calculation, Johnson sequencing, and queuing model evaluation, it seeks to enhance task execution and resource distribution, resulting in greater efficiency and prompt task completion for customers. Continued research and testing are recommended to confirm and improve the effectiveness of the DHJS algorithm across different practical cloud computing situations.
- 243 244 245 246 247
- 248 **4.0 Comparative study of different algorithms:**
- 249 **Based on factors:**

Sr.No	Scheduling Algorithm	Factors	Advantages	Disadvantages
1	First Come First Serve algorithm	Minimum waiting time	Increases average response time	Does not consider additional factors
2	Priority Algorithm	Task priority	For task scheduling , priority is considered.	Sometime lack of consistency and complex structure.
3	Round Robin Algorithm	Arrival time	Fairly distributed loads and easy to implement	Preemption is required.
4	DYNAMIC HEURISTIC JOHNSON SEQUENCING ALGORITHM :	Arrival time, Turnaround time	Minimizes the service time in cloud computing and high performance.	Complexity

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251 Based on scheduling methods:

Job	Static	Dynamic	Cloud
scheduling	scheduling	scheduling	Environment
Yes	Yes		Yes
Yes	No	Yes	Yes
Yes	No	Yes	Yes
Yes	No	Yes	Yes
	Job scheduling Yes Yes Yes Yes	JobStaticschedulingschedulingYesYesYesNoYesNoYesNo	Job schedulingStatic schedulingDynamic schedulingYesYesYesYesNoYesYesNoYesYesNoYes

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5.0 Conclusion:

The first come first serve algorithm is fair for simple applications involving less complex structure. The priority algorithm takes into account the priority based on dynamic scheduling. The round robin suits for applications where time quantum is used, All these three algorithms do not fulfils the adaptive nature of the cloud computing. The Dynamic heuristic Johnson sequencing algorithm best suits for scheduling the jobs in cloud computing. It minimizes service time and increases the performance. Considering the dynamic nature , it schedule the jobs in fairly manner,

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